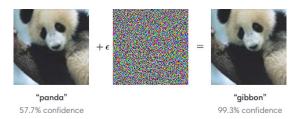
# Certifying Some Distributional Robustness with Principled Adversarial Training

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## Motivation



[Goodfellow et al. 2015]



[Athalye et al. 2017]

We want to increase the robustness of machine-learned systems

# Current Approaches

- Adversarial training heuristics: Fast but no theoretical guarantees of robustness
  - Goodfellow et al. 2015, Kurakin et al. 2016, Papernot et al. 2016, He et al. 2017, Carlini & Wagner 2017, Tramer et al. 2017, Madry et al. 2018, etc.
- Formal verification: Rigorous guarantees but very slow
  - Huang et al. 2017, Katz et al. 2017, Kolter & Wong 2017, Tjeng & Tedrake 2017, Raghunathan et al. 2018

Our goal: balance efficiency with robustness guarantees

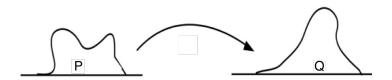
## Our Work: Principled adversarial training

• Setup: model/network weights  $\theta\in\Theta,$  feature vector X, label Y, and loss function  $\ell(\theta;X,Y)$ 

Overall idea: replace  $\ell(\theta; X, Y)$  with robust surrogate  $\phi_{\gamma}(\theta; X, Y)$ 

- For moderate levels of desired robustness and smooth losses  $\ell$ :
  - Provably fast convergence, 5-10x as fast as ERM
  - Statistical guarantees for performance on (perturbations to) the test set

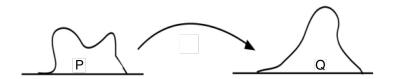
- Goal: robustness to  $\rho$ -perturbations in a Wasserstein ball
  - $c(x, x_0)$ : "cost" to perturb  $x_0$  to x (e.g.  $||x x_0||^2$ )
  - Wasserstein distance  $D_c(Q, P) := \min_{M:M_X=Q, M_{X'}=P} \mathbb{E}_M[\|X - X'\|^2]$
- Generally intractable for arbitrary  $\rho$



[Esfahani & Kuhn 2015; Shafieezadeh-Abadeh et al. 2015; Blanchet et al. 2016, Lee & Raginsky 2017]

 $\underset{\theta \in \Theta}{\mathsf{minimize}} \ \mathbb{E}_{P_0}[\ell(\theta; X, Y)]$ 

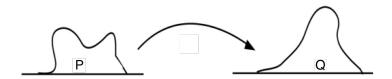
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$$\underset{\theta \in \Theta}{\text{minimize}} \quad \max_{Q} \left\{ \mathbb{E}_{Q}[\ell(\theta; X, Y)] : D_{c}(Q, P_{0}) \leq \rho \right\}$$

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• Lagrangian relaxation and its dual formulation (more robustness  $\leftrightarrow$  larger  $\rho \leftrightarrow$  smaller  $\gamma$ )

$$\underset{\theta \in \Theta}{\text{minimize}} \max_{Q} \left\{ \mathbb{E}_{Q}[\ell(\theta; X, Y)] - \underbrace{\gamma D_{c}(Q, P_{0})}_{\text{penalty}} \right\} =$$

$$\begin{split} & \underset{\theta \in \Theta}{\text{minimize }} \mathbb{E}_{P_0}[\phi_{\gamma}(\theta; X, Y)] \\ & \text{where } \phi_{\gamma}(\theta; x, y) := \max_{x' \in \mathcal{X}} \left\{ \ell(\theta; x', y) - \underbrace{\gamma \| x' - x \|^2}_{\text{penalty}} \right\} \end{split}$$

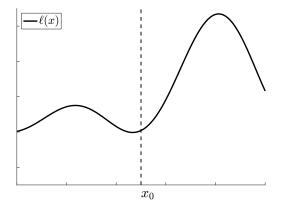
• Compare to ERM: minimize  $_{\theta \in \Theta} E_{P_0}[\ell(\theta; X, Y)]$ 

[Blanchet et al. 2016]

$$\phi_{\gamma}(\theta; x_0, y_0) := \max_{x \in \mathcal{X}} \left\{ \ell(\theta; x, y_0) - \gamma \| x - x_0 \|^2 \right\}$$

Key insight:  $(x,y) \mapsto \ell(\theta;x,y) - \gamma ||x - x_0||^2$  is strongly concave for smooth  $\ell$  and large enough  $\gamma$ 

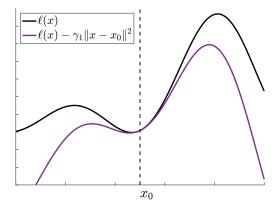
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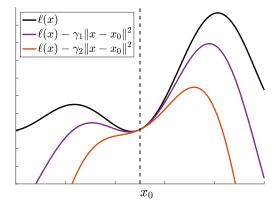
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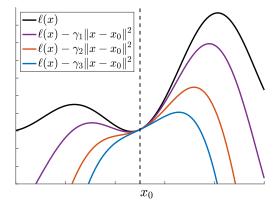
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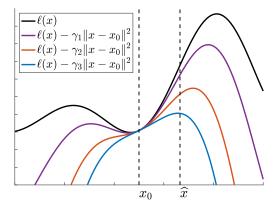
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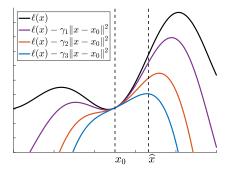
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Deep nets with smooth activations (ELUs, sigmoid, etc.) are smooth

# Optimization guarantees

Algorithm: SGD for  $\min_{\theta} E_{P_0}[\phi_{\gamma}(\theta; X, Y)]$ 

- Sample  $(x^t, y^t) \sim P_0$
- Compute adversarial example: (approximate) maximizer  $\hat{x}^t$  of  $\ell(\theta^t; x, y^t) - \gamma ||x - x^t||^2$

• 
$$\theta^{t+1} \leftarrow \theta^t - \alpha \nabla_{\theta} \ell(\theta^t; \hat{x}^t, y^t)$$

- So long as  $\nabla_x \ell(\theta; \cdot)$  is  $L_{xx}$ -Lipschitz and  $\gamma > L_{xx}$ , we can compute  $\hat{x}^t$  in  $10 \sim 20$  gradient ascent steps
- Theorem: converges at standard nonconvex-SGD rate

## Certificate of robustness

- Algorithm generalizes: we learn to prevent attacks on the test set
- $\theta_{\text{WRM}} = \text{output of Algorithm}$ ,  $\mathfrak{Comp}_n = \text{size of } \Theta$ , C = problem-dependent constant,  $\widehat{P}_n = \text{empirical training distribution}$

Theorem (Robustness Certificate) With high probability, for any  $\rho \ge 0$ 

 $\max_{Q:D_c(Q,P_0) \le \rho} \mathbb{E}_Q[\ell(\theta_{\mathrm{WRM}}; X, Y)] \le \gamma \rho + \mathbb{E}_{\widehat{P}_n}[\phi_\gamma(\theta_{\mathrm{WRM}}; X, Y)] + C \frac{\mathfrak{Comp}_n}{\sqrt{n}}$ 

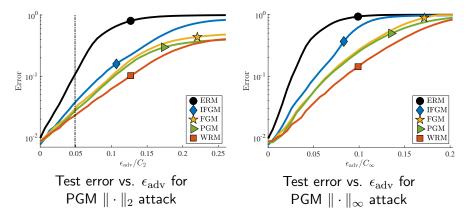
## Certificate of robustness

- Bounds can be large in practical applications due to dimension/covering-number dependence
- Alternative bound for any empirical test set  $\widehat{P}_{\rm test}$  and test examples  $(x_i^{\rm test},y_i^{\rm test})$

$$\begin{split} \frac{1}{n_{\text{test}}} \sum_{i=1}^{n} \max_{x: \|x - x_i^{\text{test}}\|^2 \le \rho} \left\{ \ell(\theta; x, y_i^{\text{test}}) \right\} &\leq \max_{Q: D_c(Q, \hat{P}_{\text{test}}) \le \rho} \mathbb{E}_P[\ell(\theta; X, Y)] \\ &\leq \gamma \rho + \mathbb{E}_{\hat{P}_{\text{test}}}[\phi_{\gamma}(\theta; X, Y)] \end{split}$$

## **MNIST** classification

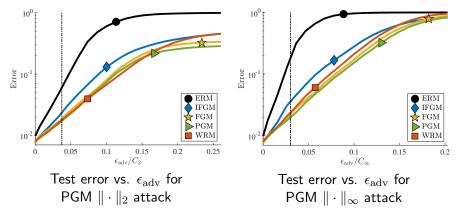
- Compare our method (WRM) with fast-gradient method (FGM), iterated FGM (IFGM), and projected gradient method (PGM)
- All models trained with 2-norm adversary



[Goodfellow et al. 2015, Kurakin et al. 2016, Madry et al. 2017]

## **MNIST** classification

• All models except WRM trained with  $\infty$ -norm adversary



# When the model misclassifies

• Minimum perturbation forcing WRM to misclassify is perceptible



Original



ERM



 $\operatorname{FGM}$ 







IFGM

PGM

WRM

# Conclusions & Future Work

- Optimization and robustness guarantees for small adversarial budgets (imperceptible perturbations)
- More empirical comparisons needed on larger models/datasets
- Statistical guarantees can be loose due to covering-number arguments
  - Recent developments: Bartlett et al. 2017, Dziugaite & Roy 2017, Neyshabur et al. 2017

Poster 7, Wednesday 11am-1pm Code: https://github.com/duchi-lab/certifiable-distributional-robustness