

Dynamic Management of Network Risk from Epidemic Phenomena

Aman Sinha, John Duchi, & Nick Bambos
Stanford University

IEEE CDC 2015

December 15, 2015

Analyzing Epidemics

- Classic models (SIS, SIR) now generalized to probabilistic models of infection (Ganesh et al. 2005)
- Widely applicable - digital/biological viruses, network router faults, social media influence, etc.
- Control
 - Optimization approaches explicitly include budget constraints (Gourdin et al. 2011, Preciado et al. 2013, Preciado et al. 2014)
 - Our methods also deal with decentralization and robustness

Outline

Model Framework

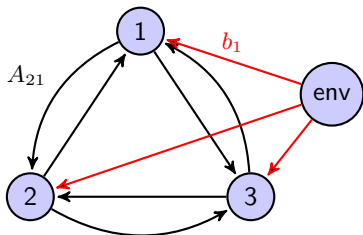
Proposed Approach

Experiments

Conclusions & Future Work

System Dynamics

- SIS epidemic model as a continuous-time Markov process



$$\mathbf{s} = [s_1, s_2, \dots, s_N]^T \in \{0, 1\}^N$$

$$s_i(t) : \begin{cases} 1 \rightarrow 0 & \text{at rate } r_i \\ 0 \rightarrow 1 & \text{at rate } \mathbf{e}_i^T \mathbf{A} \mathbf{s}(t) + \\ & \mathbf{e}_i^T \mathbf{b} s_{env}(t) \end{cases}$$

$$s_{env}(t) : 1 \rightarrow 0 \text{ at rate } r_{env}$$

- Instantaneous energy of infection

$$P(\mathbf{1}^T \mathbf{s}(t) > 0) \leq \sqrt{N} \|\mathbf{z}(t)\|_2$$

$$\begin{aligned} \dot{\mathbf{z}}(t) &= D \mathbf{z}(t) + \mathbf{b} e^{-r_{env} t} s_{env}(0), \\ \mathbf{z}(0) &= \mathbf{s}(0), \quad D := A - \text{diag}(\mathbf{r}) \end{aligned}$$

Problem Setup

- Control environmental impact on system via limited budget at discrete intervals
 - Discretize dynamics: $\mathbf{x}(k) := \mathbf{z}(kh)$
 - Control \mathbf{b} w.r.t budget constraints

$$\mathbf{u}(k) = (\mathbf{b} - \mathbf{w}(k))e^{-r_{env}kh} s_{env}(0)$$
$$\mathbf{0} \preceq \mathbf{w}(k) \preceq \mathbf{b}, \quad \|\mathbf{w}(k)\|_1 \leq c,$$

- Minimize cumulative energy of infection via MPC

$$\int_0^\infty P(\mathbf{1}^T \mathbf{s}(t) > 0) dt \leq \sqrt{N} \int_0^\infty \|\mathbf{z}(t)\|_2 dt \approx \sqrt{N} \sum_{k=0}^T \|\mathbf{x}(k)\|_2$$

$$\text{minimize } J_m := \sqrt{N} \sum_{k=m+1}^{T+m} \|\mathbf{x}(k)\|_2$$

subject to (dynamics, constraints)

Problem Setup (contd.)

- Centralized solution is inefficient for large N and network connectivity might not be known perfectly
- Decentralization - split system into M (possibly unequal) subsystems
- Robustness - off-diagonal blocks of A are known only within some uncertainty region

Outline

Model Framework

Proposed Approach

Experiments

Conclusions & Future Work

Proposed Approach

Sinha, Duchi, & Bambos. Dynamic Management of Network Risk

Reduced-Order Models

- Each subsystem models the other subsystems' dynamics through reduced-order models (decentralization/accuracy tradeoff)
- Standard model reduction procedure (e.g. via balanced truncation, Safonov et al. 1988)
 - Procedure outputs compression and expansion operators
 - Analogous to similarity transformation
- Local problem for subsystem i (with state \mathbf{x}_r^i , control \mathbf{u}_r^i):

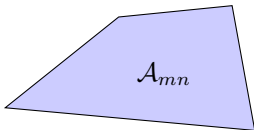
$$\text{minimize } J_m^i := \sqrt{N} \sum_{k=m+1}^{T+m} \|\mathbf{x}_r^i(k)\|_2$$

subject to (reduced dynamics, reduced constraints)

Robust Formulation

- Polytopic/"scenario" uncertainty sets (efficiency/robustness tradeoff)

$$\mathcal{A}_{mn} = \{C | C = \sum_{k=1}^{L_{mn}} \mu_k A_{mn}(k), \mu_k \geq 0, \sum_{k=1}^{L_{mn}} \mu_k = 1\}$$



- Straightforward generalization for model reduction via generalized balanced truncation (replace Lyapunov eq. with LMI)
- Robust counterpart for local problem ($\min \sup_{\mathcal{A}} J_m^i$) is an SOCP
 - Requires linearizing dynamics s.t. $\mathbf{x}_r^i(k)$ is affine in A

Outline

Model Framework

Proposed Approach

Experiments

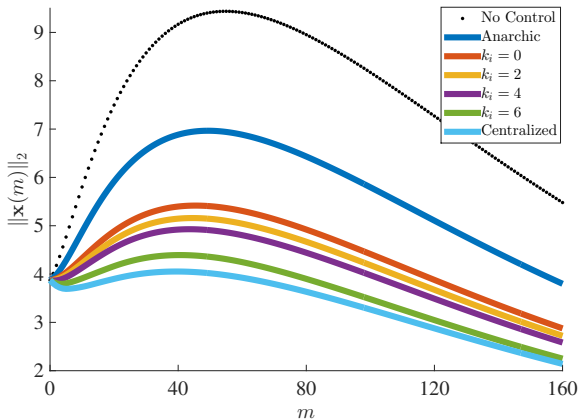
Conclusions & Future Work

Experiments

- $N = 24$, $M = 3$, equal subsystem sizes, random adjacency matrices and recovery rates
- Environment heals, but at a slower rate than the system
 - $s_{env}(0) = 1$, $r_{env} = 0.2 < -\lambda_i(D) \in [0.33, 1]$
- We vary the order of reduced models, $k_i = \{0, 2, 4, 6, 8\}$
- Compare with no control, anarchy (each subsystem has budget c/M)

Experiments (contd.)

- Cooperation/dynamic budget allocation assuages overshoot
- Larger k_i yields better performance



Outline

Model Framework

Proposed Approach

Experiments

Conclusions & Future Work

Conclusions & Future Work

- Developed framework for dynamic network protection incorporating budget constraints, decentralization, and robustness to uncertainty
- Tradeoffs between efficiency/robustness and decentralization/optimalty
- Many avenues worth further research
 - Uncertainty sets with greater scalability
 - Optimal decentralized schemes for partitioning budgets between subsystems
 - Dynamic network topologies